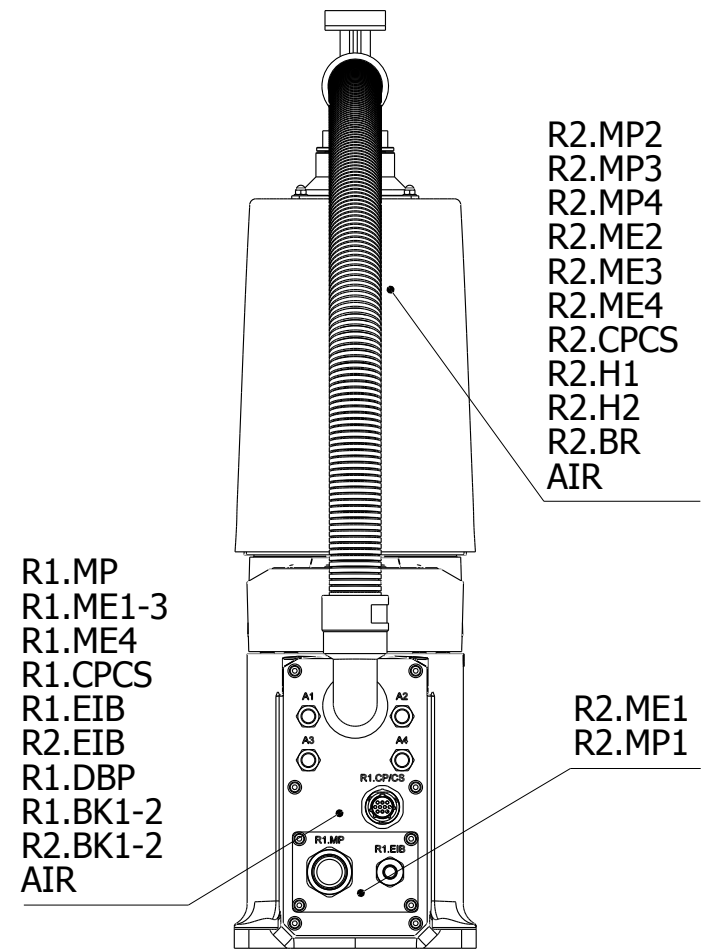
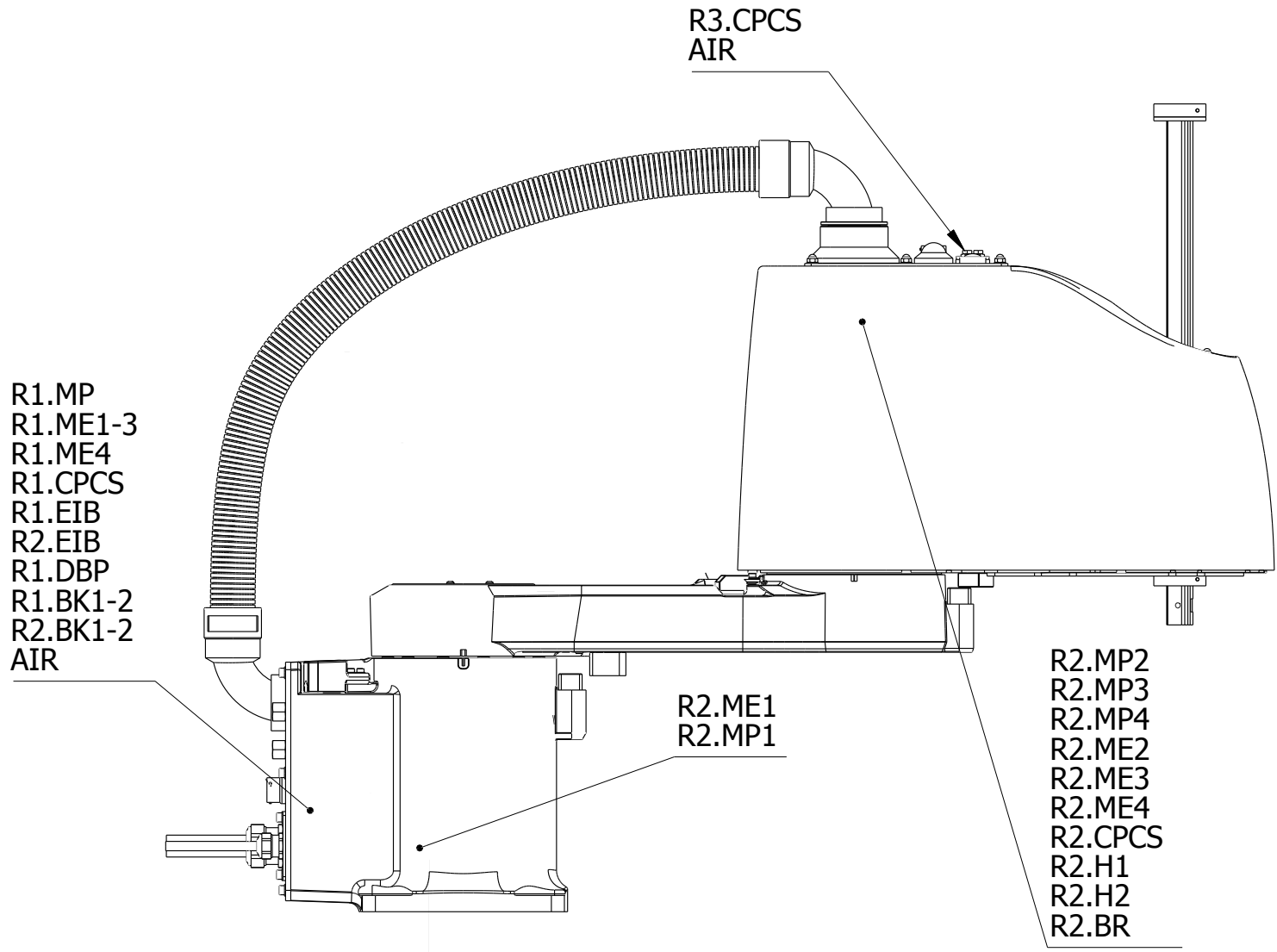


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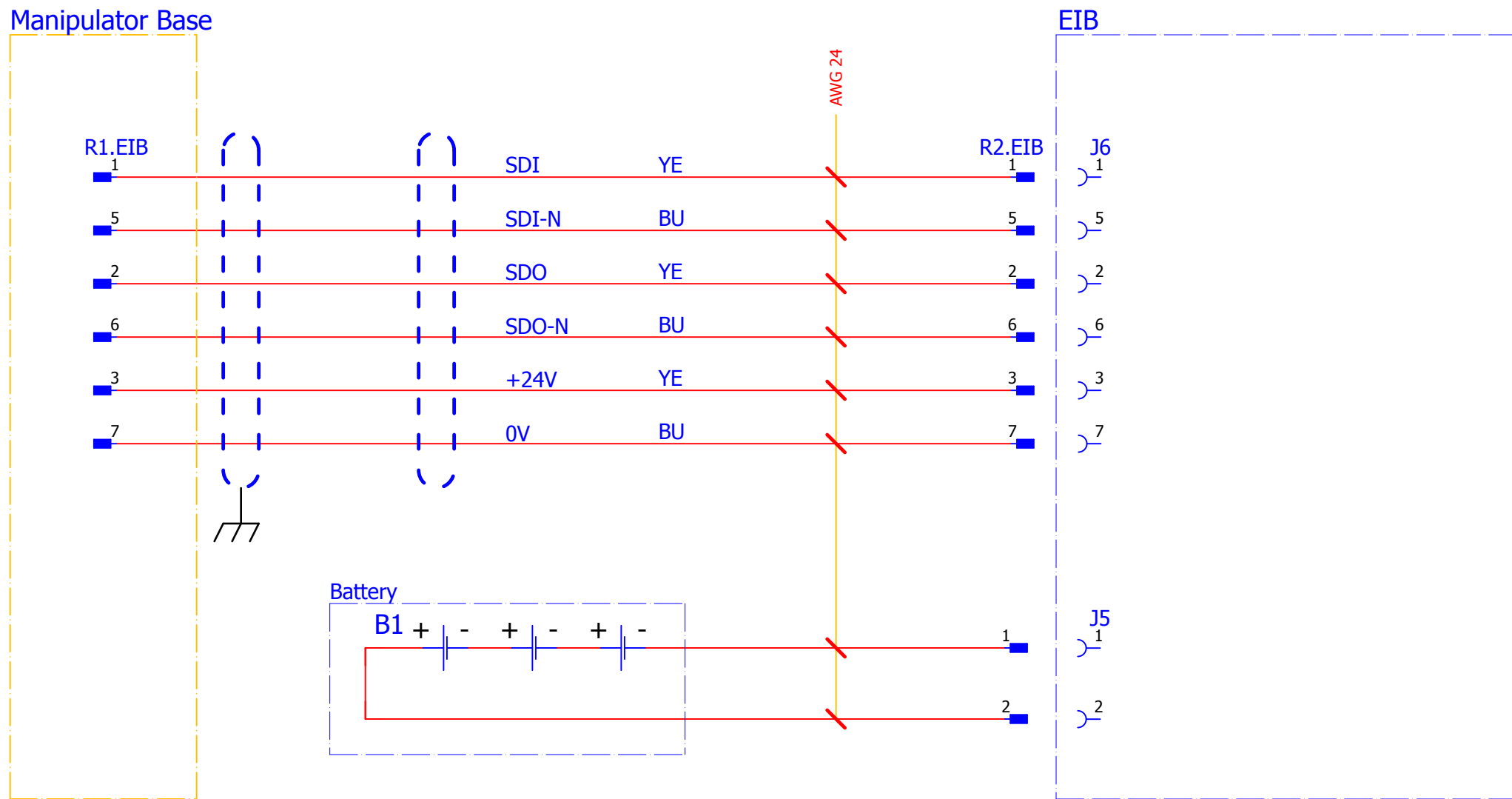
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Conn Point Location

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Manipulator Base

R1.CP/CS

- A
- B
- C
- D
- E
- F
- G
- H
- J
- K

- YE
- BU
- YE
- BU
- YE
- BU
- YE
- BU
- YE
- BU

AWG 24

R2.CPCS

- 1
- 2
- 3
- 4
- 5
- 6
- 7
- 8
- 9
- 10

- YE
- BU
- YE
- BU
- YE
- BU
- YE
- BU
- YE
- BU

AWG24

Manipulator Arm 2

R3.CP/CS

- A
- B
- C
- D
- E
- F
- G
- H
- J
- K

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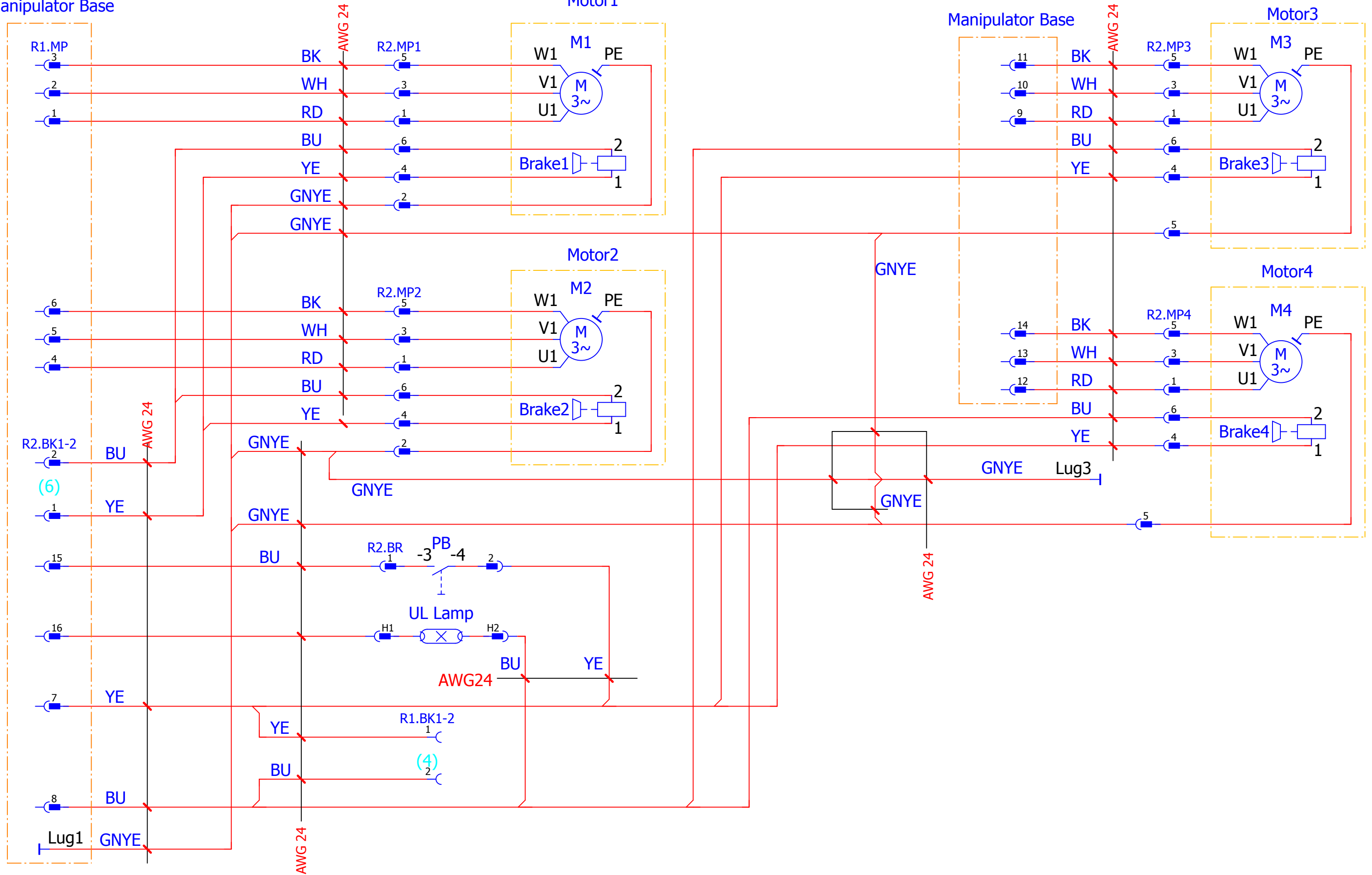
Motor1

Manipulator Base

Motor3

Motor2

Motor4



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IRB910SC  
Cable Harness Main

Plant: =  
Location: +  
Sublocation: +

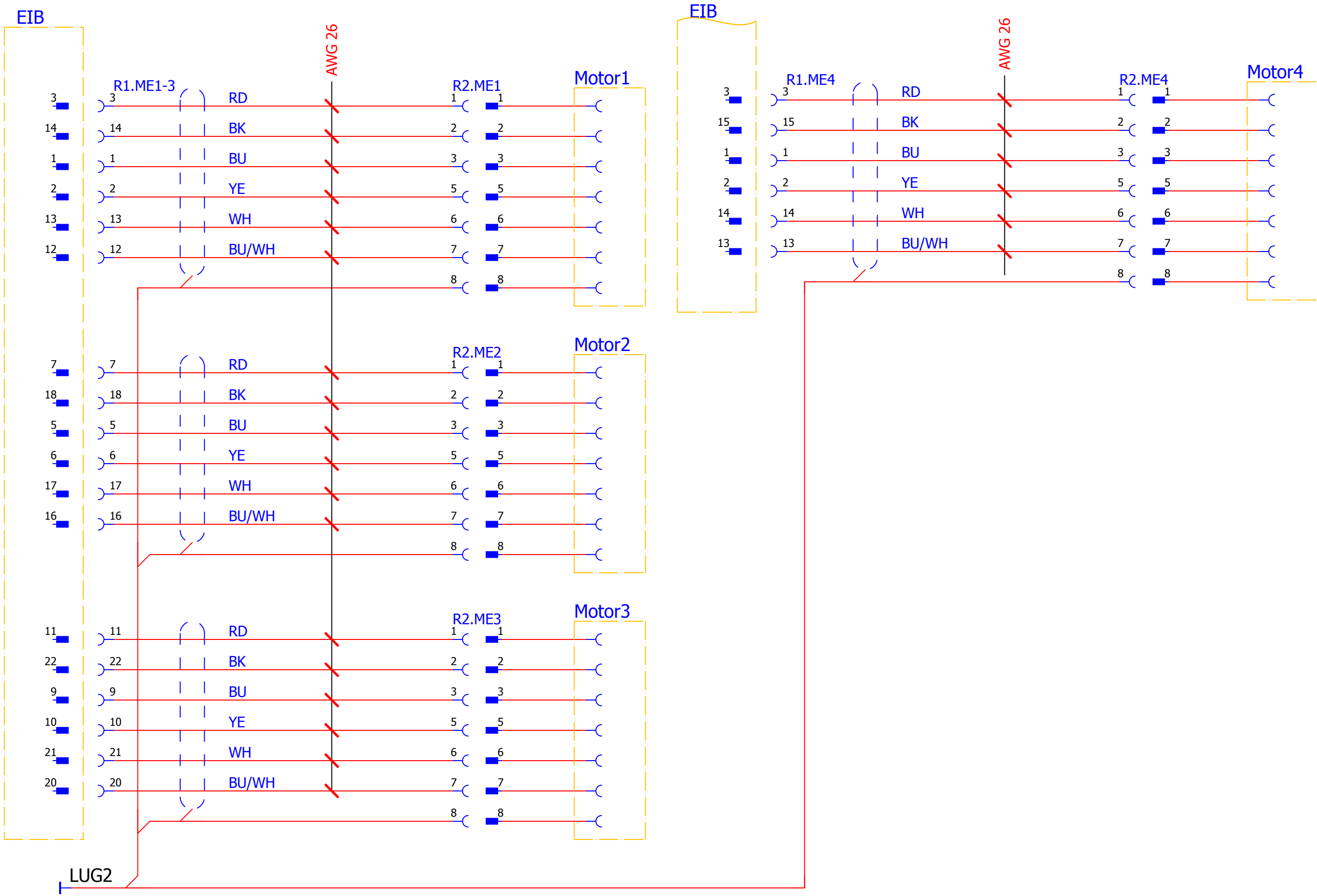
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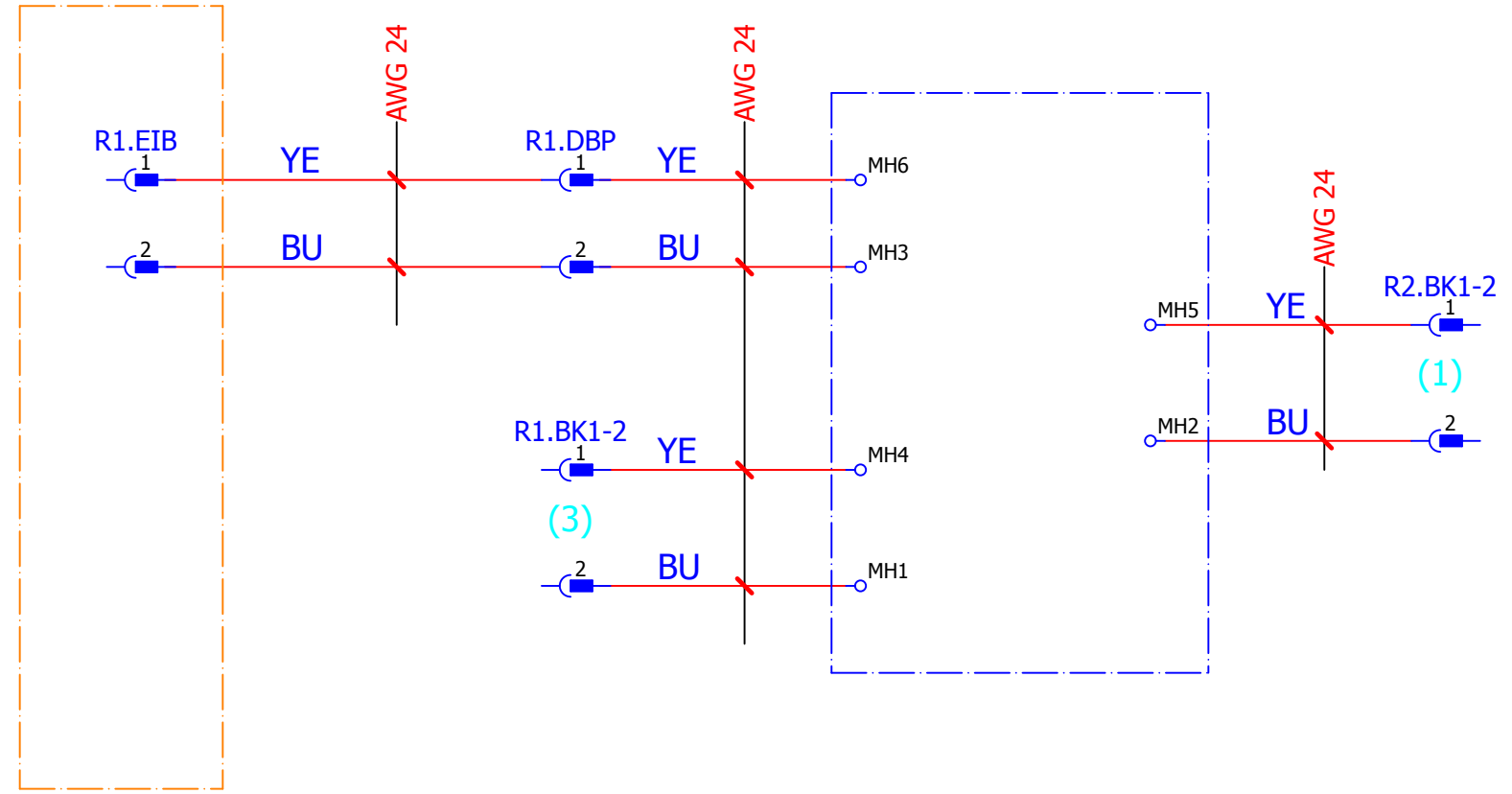
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Cable Harness EIB

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Manipulator base



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